

LEHRSTUHL FÜR INFORMATIK 2 👩

RWTH Aachen · D-52056 Aachen · GERMANY

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Solution

(10 points)

Let P and P' be safety properties. Prove that  $BadPref(P) \cap BadPref(P') = BadPref(P \cup P')$ . Solution:

$$\begin{aligned} \hat{\sigma} \in BadPref(P) \cap BadPref(P') \iff P \cap \left\{ \sigma' \in \left(2^{AP}\right)^{\omega} \mid \hat{\sigma} \in pref(\sigma') \right\} &= \emptyset \\ & \wedge P' \cap \left\{ \sigma' \in \left(2^{AP}\right)^{\omega} \mid \hat{\sigma} \in pref(\sigma') \right\} &= \emptyset \\ \iff \left( P \cup P' \right) \cap \left\{ \sigma' \in \left(2^{AP}\right)^{\omega} \mid \hat{\sigma} \in pref(\sigma') \right\} &= \emptyset \\ \iff \hat{\sigma} \in BadPref(P \cup P'). \end{aligned}$$

Consider the linear-time property P over  $AP = \{a, b\}$ :

" $(\neg a \land \neg b)$  holds infinitely often and  $(a \land b)$  never holds and between any two occurrences of  $(\neg a \land \neg b)$ , the number of states where b holds is even."

- 1. Provide an NBA  $\mathcal{A}$  over  $2^{AP}$  such that  $\mathcal{L}_{\omega}(\mathcal{A}) = P$ . Hint: Parts (b) and (c) can be solved without a solution for part (a).
- 2. Formally prove or disprove the following statements:
  - *P* is a safety property.
  - *P* is a liveness property.
- 3. Let  $\mathcal{A}'$  be an NBA over  $2^{AP}$ . Then  $P' = \mathcal{L}_{\omega}(\mathcal{A}')$  is the linear-time property defined by  $\mathcal{A}'$ . Is it always the case that there exists an LTL-formula  $\varphi$  such that  $P' = Words(\varphi)$ ? Justify your answer!

### Solution:

1. An NBA  $\mathcal{A}$  over  $2^{AP}$  with  $\mathcal{L}_{\omega}(\mathcal{A}) = P$  is depicted below:



2. P can be characterized by the  $\omega$ -regular expression E derived as follows:

$$L_{q_0,q_2} = (\{a\} + \{b\})^* . \emptyset$$
  

$$L_{q_2,q_2} = (\{b\}.\{a\}^* . \{b\}.\{a\}^*)^* . \emptyset$$
  

$$E = L_{q_0,q_2}.L_{q_2,q_2}^{\omega} = (\{a\} + \{b\})^* . (\emptyset.(\{b\}.\{a\}^* . \{b\}.\{a\}^*)^*)^{\omega}.$$

We disprove that P is

- a safety property:  $\sigma = \emptyset\{a\}^{\omega} \in (2^{AP})^{\omega} \setminus P$ . Note that for all  $\hat{\sigma} \in pref(\emptyset\{a\}^{\omega})$  it holds that  $\hat{\sigma}.\emptyset^{\omega} \in P$ . Thus no bad prefix exists for  $\sigma$  and P is not a safety property.
- a liveness property:  $\{a, b\} \notin pref(P)$ . Hence  $pref(P) \neq (2^{AP})^*$ .

3. No. LTL is strictly less expressive than the class of  $\omega$ -regular languages. See Remark 5.43.

(4 + 4 + 2 points)

Let  $\varphi = (a \land \bigcirc a) \mathsf{U}(a \land \neg \bigcirc a)$  be an LTL-formula over  $AP = \{a\}$ .

- 1. Compute all elementary sets with respect to  $\varphi$ .
- 2. Construct the GNBA  $\mathcal{G}_{\varphi}$  according to the algorithm from the lecture such that  $\mathcal{L}_{\omega}(\mathcal{G}_{\varphi}) = Words(\varphi)$ .
- 3. Give an  $\omega$ -regular expression E such that  $\mathcal{L}_{\omega}(\mathcal{G}_{\varphi}) = \mathcal{L}_{\omega}(E)$ .

### Solution:

1. The elementary sets are:

	a	$\bigcirc a$	$a \wedge \bigcirc a$	$a \wedge \neg \bigcirc a$	$\varphi$
$B_1$	0	0	0	0	0
$B_2$	0	1	0	0	0
$B_3$	1	0	0	1	1
$B_4$	1	1	1	0	0
$B_5$	1	1	1	0	1

2. The GNBA  $\mathcal{G}_{\varphi} = (Q, 2^{AP}, \delta, Q_0, \mathcal{F})$  is defined by:

$$Q = \{B_1, B_2, B_3, B_4, B_5\}$$
$$Q_0 = \{B_3, B_5\}$$
$$\mathcal{F} = \{F_{\varphi}\}$$
$$F_{\varphi} = \{B_1, B_2, B_3, B_4\}$$



The transition relation  $\delta$  is given by the following graph:

3. We derive  $\mathcal{L}_{\omega}(\mathcal{G}_{\varphi}) = Words(\varphi) = \{a\}^{+} \emptyset \left(2^{AP}\right)^{\omega}$ .

(3 + 4 + 3 points)

Compute  $Sat_{sfair}(\Phi)$  for the CTL-formula  $\Phi$  and the strong fairness assumption sfair:

$$\Phi = \exists \Box a$$
  
sfair =  $\Box \diamond a \to \Box \diamond \exists (\neg a) \mathsf{U} (\forall \bigcirc b)$ 

where TS over  $AP = \{a, b\}$  is given by:



Proceed in the following steps:

- 1. Determine  $Sat (\exists (\neg a) \cup (\forall \bigcirc b))$  (without fairness).
- 2. Determine  $Sat_{sfair}(\exists \Box true)$ .
- 3. Determine  $Sat_{sfair}(\Phi)$ .

#### Solution:

1.  $Sat(\exists (\neg a) \mathsf{U}(\forall \bigcirc b))$ : Consider the state subformula  $\forall \bigcirc b$ . Then  $Sat(\forall \bigcirc b) = \{s_5\}$ . Further,  $Sat(\neg a) = \{s_0, s_1, s_2, s_5\}$ . Using the backward search starting in  $s_5$  we derive  $Sat(\exists (\neg a) \mathsf{U}(\forall \bigcirc b)) = \{s_0, s_1, s_2, s_5\}$ .

Now we relabel states in Sat(a) with  $a_1$  and those in  $Sat(\exists (\neg a) U(\forall \bigcirc b))$  with  $b_1$  to encode the strong fairness constraint in the transition system:



- 2. Compute  $Sat_{sfair}(\exists \Box true)$ :
  - The SCCs of G[true] of TS[true] are:

$$\begin{array}{ll} C_1 = \{s_0, s_3\} & C_2 = \{s_0, s_1\} \\ C_3 = \{s_3, s_4\} & C_4 = \{s_2, s_5\} \\ C_{1,2} = \{s_0, s_1, s_3\} & C_{1,3} = \{s_0, s_3, s_4\} \\ \end{array}$$

Then  $T = \{C_1, C_2, C_{1,2}, C_{1,2,3}, C_4\}$ . Some examples for this: -  $C_3 \notin T$  because  $C_3 \cap Sat(a) = \{s_3\}$  but  $C_3 \cap Sat(\exists (\neg a) \mathsf{U}(\forall \bigcirc b)) = \emptyset$ . -  $C_1 \in T$  because  $C_1 \cap Sat(a) = \{s_3\}$  and also  $C_1 \cap Sat(\exists (\neg a) \mathsf{U}(\forall \bigcirc b)) = \{s_0\}$ . Then  $Sat_{sfair}(\exists \Box \mathsf{true}) = \{s \in S \mid Reach_{TS}(s) \cap \bigcup T \neq \emptyset\} = S$ . Extend the labeling accordingly by a fresh atomic proposition  $a_{fair}$  (omitted here).

- 3. Compute  $Sat_{fair}(\exists \Box a)$ :
  - Then G[a] of TS[a] is the graph



Further, there is only one SCC in G[a]:  $C_3 = \{s_3, s_4\}$ . But as  $C_3 \notin T - C_3$  satisfies  $a_1$  infinitely often, but never  $b_1$  — it is not fair. Hence  $Sat_{sfair}(\exists \Box a) = \emptyset$ .

## Solution 5a

Consider the two transition systems  $TS_1$  and  $TS_2$ :



- 1. Prove or disprove  $TS_1 \sim TS_2$ .
- 2. Prove or disprove  $TS_1 \simeq TS_2$ .

### Solution:

- 1.  $TS_1 \not\sim TS_2$ : A distinguishing CTL-formula is  $\forall \Box (a \rightarrow \exists \bigcirc (a \land b))$ . Then  $TS_1 \models \Phi$  and  $TS_2 \not\models \Phi$  (because of  $t_1$ ).
- 2.  $TS_1 \simeq TS_2$ :
  - $TS_1 \leq TS_2$  with simulation relation  $\mathcal{R} = \{(s_0, t_0), (s_1, t_4), (s_2, t_3), (s_3, t_5)\}$ :



•  $TS_2 \leq TS_1$  with simulation relation  $\mathcal{R} = \{(t_0, s_0), (t_1, s_1), (t_2, s_1), (t_4, s_1), (t_3, s_2), (t_5, s_3)\}$ :



Hence,  $TS_1 \preceq TS_2$  and  $TS_2 \preceq TS_1$ . Therefore  $TS_1 \simeq TS_2$ .



((2+1) + (3+3+1) points)

# Solution 5b

(10 points)

Let  $\Phi = \forall a \mathsf{U} (\neg \exists \Box b)$ . Prove or disprove the following statement:

There exists an LTL-formula  $\varphi$  that is equivalent to  $\Phi.$ 

## Solution:

Let  $\Phi = \forall a \mathsf{U} (\neg \exists \Box b)$ . Then  $\varphi = a \mathsf{U} \neg \Box b$  (by Thm. 6.18). We prove that  $\Phi \equiv \varphi$ :

$$s \models \Phi \iff \forall \pi \in Paths(s). \exists k \ge 0. \ (\pi[k] \models \neg \exists \Box b \land \forall j < k. \ \pi[j] \models a)$$
  
$$\iff \forall \pi \in Paths(s). \exists k \ge 0. \ (\pi[k] \models \forall \Diamond \neg b \land \forall j < k. \ \pi[j] \models a)$$
  
$$\iff \forall \pi \in Paths(s). \exists k \ge 0. \ (\forall \pi' \in Paths(\pi[k]). \exists i \ge 0. \ \pi'[i] \models \neg b \land \forall j < k. \ \pi[j] \models a)$$
  
$$\iff \forall \pi \in Paths(s). \exists k \ge 0. \ (\pi[k] \models \Diamond \neg b \land \forall j < k. \ \pi[j] \models a)$$
  
$$\iff s \models a \cup \Diamond \neg b$$
  
$$\iff s \models a \cup \neg \Box b.$$